

ARTICLE HANDLING DEVICE

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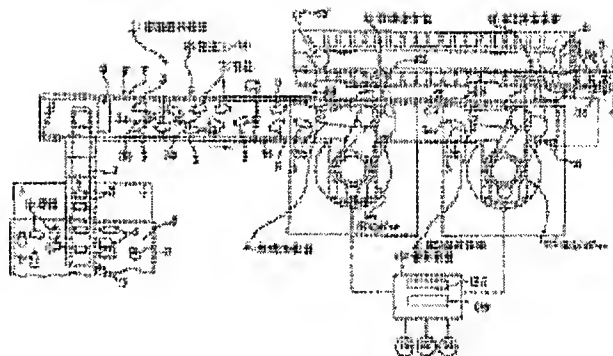
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□ JP3077564 (B2)

Abstract of JP 8336784 (A)

PURPOSE: To provide an article handling device high in handling capacity while suppressing the increase of an installation space. **CONSTITUTION:** Two robots 12, 12' are disposed in the conveying course of a carrying conveyor 2. When a first container 3 and a second container 3 are conveyed into a first hold position A, a control device 13 holds these containers 3 by a first robot 12 on the basis of the image of these containers 3 photographed by a camera 14 and then delivers them in a first release position B on a discharge conveyor 4. As to third and fourth containers 3, the control device 3 makes them pass through the first hold position A, and at the time of reaching a second position A', the third and fourth containers 3 are held by a second robot 12' and delivered in a second release position B' on the discharge conveyor 4.



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